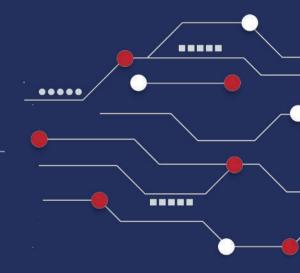


FLOORPUL®





From the cooperation between Floorpul, that found it's roots in the cleaning sector and Muratec, the Japanese reality active on the electronic development

FLOORPUL

We want to be a landmark for the environment and for your welness, by making high efficiency scrubbers with an inspired design.



for industrial solutions, a new autonomous drive scrubber is born, that combines all the main values of the two partners.



powered by

Muratec

We shall strive to expand the boundaries of technological advancement, provide meaningful products that enrich the lives of our customers, bring prosperity to each of our employees and lead society to a better tomorrow.

The teaching modes of the **-auartz*

The technology which is at the base of the functioning, divides itself in two different stages:

- Learning of the task to carry out by the machine and memorization of this task as a route.
- Repetition of the route from the starting point, assigned during the Teaching mode.



R-Quartz allows two learning ways:

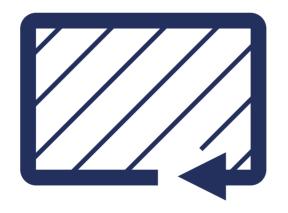
Playback

To use the Playback mode the operator first has to make a complete cleaning cycle the same as it will be made autonomously by the machine.

All the route details and the settings

(water carriage, brushes pressure, etc.) will be memorized and faithfully repeated. "Playback" is useful when cleaning narrow and congested areas, with few variations of the environment configuration





Perimeter

With Perimeter mode, the operator just needs to define the outer perimeter of the area to be cleaned and the machine will manage optimally the cleaning of the inner areas.

"Perimeter" is a very quick learning

method, interesting when dealing with large areas with few elements on their inside, which environmental configuration is regularly changed. On this mode, the route's starting and ending points needs to coincide.

Work sequencies and Teaching combinations

When starting an autonomous work cycle, the operator can create a sequence that will automatically combine more memorized routes even in different modes. Moreover, this function has the big advantage to give the programmer the chance to create shorter and so more flexible routes.

The learning and repetition stages can be stopped by the operator whenever there is the need to, without this affecting the remaining route.

If Paulariz finds a new obstacle it will try to avoid it and will resume its route as soon as it is possible. If this is not possible, a notification will be send to the operator through the TELEMATICS system.



Controls Console



To allow an interesting productivity in autonomous mode, R-auartz was designed based on the QUARTZ 66-80 model, a high level performances and technical features machine.

- 24V 330A lithium battery pack, which grants up to 6 hours of work autonomy.
- Fast charge in 5 hours.
- Possibility of a 185 Ah Gel battery pack, with an autonomy of 3 hours.



Speed up to 4 km/h, (very fast for an autonomous scrubber).



- On-board dedicated tank for the detergent.
- Thanks to the "3SD", it is possible to precisely adjust the consumptions, granting up to a 4 hours autonomy.



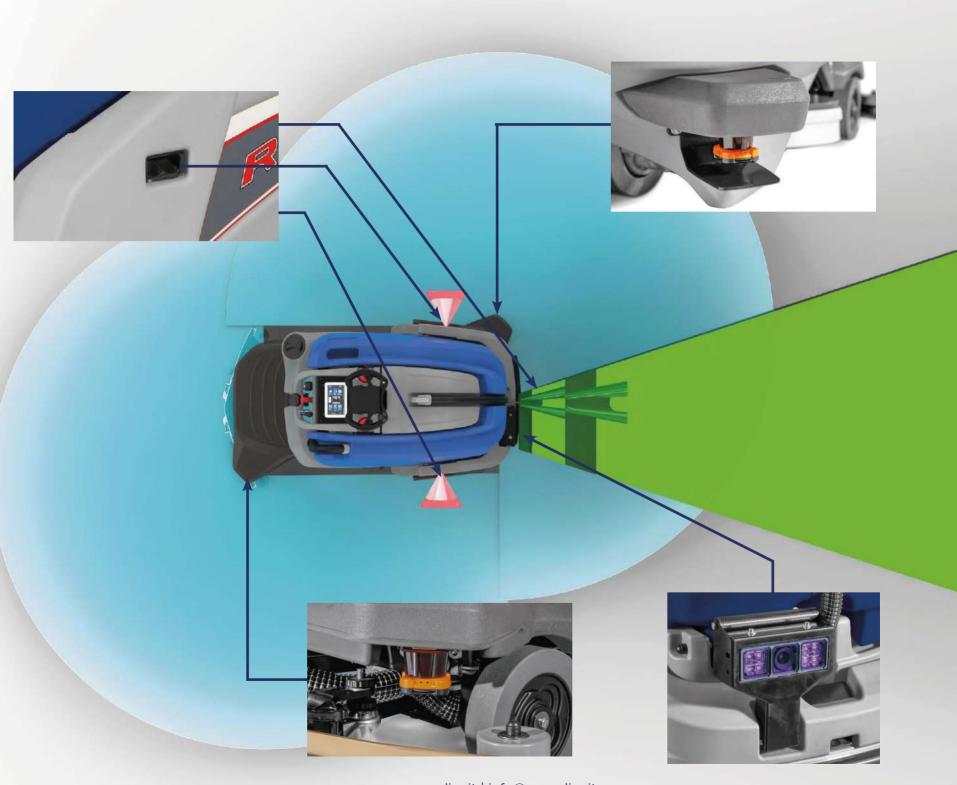
3 power stages for the suction motor in order to reduce its noise up to 67 dB.

Brushes pressure variable up to 52 kg

Work safely

R-DUARTZ is provided with 3 safety systems wich work simultaneously and are able to make it move in total autonomy. Furthermore, 3 bumpers are installed on the sides of the machine. When touching a sudden obstacle, the bumpers immediately make the machine stop.



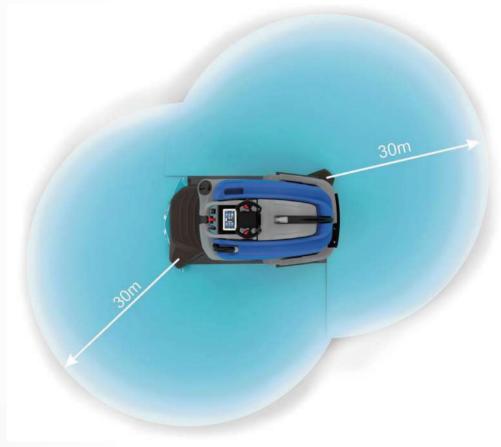


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LIDAR sensors

which allow a very accurate 360° horizontal mapping, at an height from the ground of 200 mm. The LIDAR sensor grant the machine a complete view when turning.

In the learning stage, they allow to make a precise mapping of the route environment. The machine is then able to position itself in the space and quickly manage any eventual unexpected event



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The 3D camera

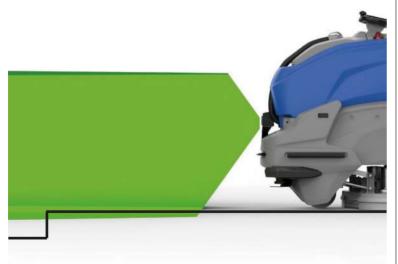
In the front part of the machine a **3D** camera is positioned.

The wide sight range allows to detect obstacles at an height up to 700mm from the floor and floor variations, even large ones, i.e. steps.

Even in presence of obstacles, as much as possible, R-auarz will try to avoid them and resume its route.

Ultrasonic sensors

The **3 ultrasonic sensors**, placed on the front and side parts, provides an additional safety in the management of eventual obstacles that were not identified during the learning stage. These sensors are also able to detect the presence of transparent obstacles such as windows and shop's glass walls







Thorugh the Telematics the machine is always in touch with the operator.

Thanks to this device, the operator can always see the map's sequence that the machine is performing, the remaining time to the end of the task and the indications related to the eventual issues, error or warnings that the machine reports.

Moreover, in case of problems, the operator will be warned real time through notifications transmitted directly on the smartphone.



Technical data

Working capacity: 3425 m2/h

Battery autonomy: 6 h

Cleaning width: 685 mm

Squeegee width: 900 mm

Brushes motor: 2x350 Watt

Brushes pressure: max 52 Kg

Brushes speed: 160 giri/min

Disc brushes: 2x355 mm Speed 4.5 km/h

Maximum gradient: 10%

Suction motor: 570 Watt

Suction vacuum: 160 mbar

Solution tank: 100 l Recovery tank: 106 l

Detergente tank: 7 l

Machine dimensions: L: 1634 mm

W: 922 mm

H: 1350 mm

Machine weight (with batteries Li): 340 kg

Power supply 24V / 330 Ah

Battery compartment x2: 532 mm

W: 187 mm

H: 325 mm

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Class:

Protection level: IP X3

Loudness: liv 1: 67 dB (A)

liv 2: 70 dB (A)

liv 3: 76 dB (A)





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